

Automotive BMS for:

- Pure Electric vehicle
- Hybrid Electric vehicle
- High Performance Electric vehicle
- Electric motorbikes

INTRODUCTION

The networked LiBAL n-BMS has been developed around the new communication standard isoSPI, which essentially does not require programmable processors on CMU's (Slave PCB) in the BMS network. In any application, this is a huge advantage, because it does not require software on the CMU and therefore greatly simplifies in-field maintenance. In addition, the isoSPI communication network ensure the most cost efficient communication circuit in the market.

The n-BMS is developed to meet all relevant automotive requirements. ISO 26262 compliant design with key components such as Processor, ASIC and PSU carefully selected to meet the functional safety at ASIL C level.

The n-BMS can be configured with up to 32 CMU's. Each CMU can monitor up to 12 cells in series and thus the n-BMS can monitor in total up to 384 cells in series.

The n-BMS can measure temperature with an accuracy up to +/-1 C and measure cell voltages with an accuracy of +/-1,5 mV, throughout the entire temperature range (-40 to +85 °C).

The n-BMS Creator™ software, enable the battery designer to create a unique Battery design based on the n-BMS hardware. The n-BMS Creator™ software facilitates a unique safety strategy, battery performance optimisation, charge time reduction as well as ensuring the best possible battery life.

SAFETY

- ISO 26262 rated components and design
- Self-test and redundancy in safety critical measurement circuits
- Open circuit detection

BATTERY LIFE

- High frequency sampling of current (100 mS) allows optimal detection of pulses
- Powerful and intelligent dissipative balancing at 200mA per cell
- 40° to +85°C operational range

PERFORMANCE

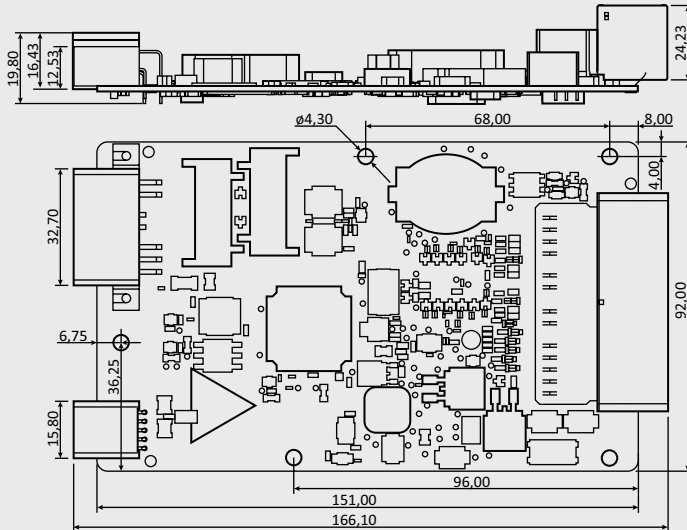
- ±1.5 mV accuracy in the complete temperature range (cell voltage)
- Optimized low power consumption mode
- ±1 °C accuracy in temperature measurement
- Advanced SOC algorithm with OCV compensation
- Advanced SOH algorithm
- Advanced SOP Algorithm

USABILITY

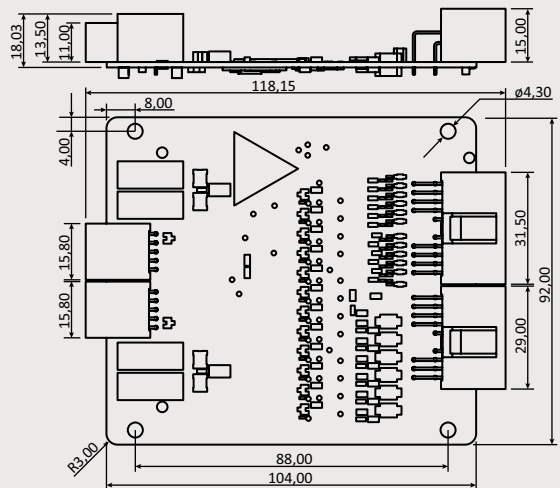
- RTC + logging of events, errors and warnings
- BMS Creator PC tool for easy configuration
- Optional current sensing (Hall effect or Shunt)
- CAN UDS tool

Applications





n-BMS MCU



n-BMS CMU

Dimensions in MM

PARAMETERS

Master Control Unit (MCU)

Power supply
Number of CMU's supported
Number of cells in series for total system
Range of high voltage measurement
Accuracy of high voltage measurement
Range of current measurement input Shunt
Accuracy of current measurement input Shunt
Range of current measurement input (Hall effect sensor)
Accuracy of current measurement input (Hall effect sensor)
Accuracy of temperature (NTC)
Ground fault detection (leakage) levels
Standby Consumption
Active Consumption
Communication interface, master-slave
Supported CAN communication type
Supported CAN speeds
Number of CAN ports
External GPIOs
Charger control interfaces

Cell Monitoring Unit (CMU)

Number of cells per unit
Detectable cell voltage
Cell balancing topology
Cell balancing current
Cell voltage typical sampling time
Accuracy of single cell voltage
Range of Temperature measurements
Accuracy of cell temperature (NTC)
Communication interface
Standby Consumption
Active Consumption
Patents

SPECIFICATIONS

6-35 V
1-32
384
0 - 1000 VDC
±1 VDC
±150 mV
±1.0 mV -40 – 85 °C
0.0 – 5.0 V, 0.0 -2.5 V current in, 2.5 V – 5.0 V current out
±1.5 mV -40 – 85 °C
±1 °C -40 – 85 °C
250/500/1000 Ω/V Between GND and HV+/-
<8,5 mW at 12V supply
<3,5 W at 12 V supply
isoSPI
CAN 2.0A/B 11 bit and 29 bit IDs
125, 250, 500, 1k kbit/sec
2, one isolated CAN, one non-isolated CAN.
16 (Active Low)
CAN
3-12 Cells (minimum 11 V, to power the CMU)
0 - 5 VDC
Dissipative
200 mA, at cell voltage 4.2 V
100 ms
±1.5 mV from -40 to +85 °C
-40 to +125 °C
±1 °C -40 – 85 °C
isoSPI (Max. 5 m shielded cable between boards)
<269µW (with 12 cells @ 3,2 V)
<326 mW (with 12 cells @ 3,2 V)
ZT 200780048774,EP 0781788.6,US 8.350.529

